

# Database Systems

(資料庫系統)

November 19/21, 2007

Lecture #8

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## Announcement

- Assignment #4 on the course webpage, due 11/28.

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# Tree-Structured Indexing

## Chapter 10

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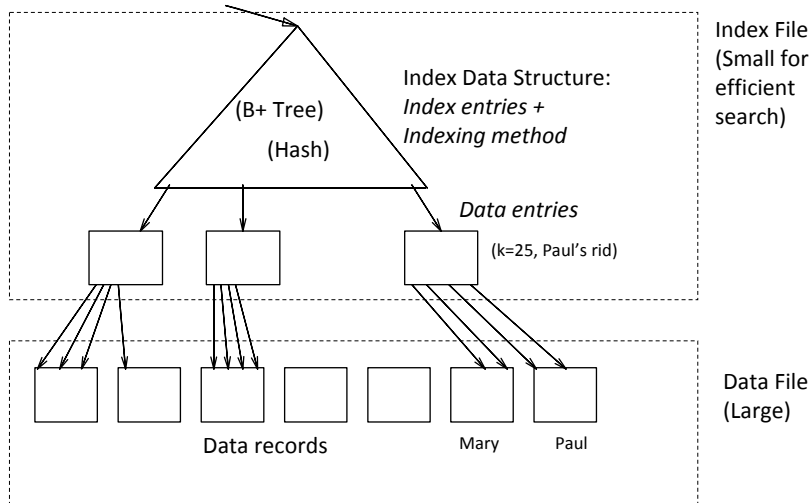
## Outline

- Motivation for tree-structured indexes
- ISAM index
- B+ tree index
- Key compression
- B+ tree bulk-loading
- Clustered index

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## Review: Indexing Example

Search key value: find employees with age = 25



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## Review: Three Alternatives for Data Entries

- As for any index, 3 alternatives for data entries  $k^*$ :
  - (1) Clustered Index: data entry is data record (sorted by  $k$ )
  - (2) Unclustered Index: data entry separated from data record:  $\langle k, \text{rid of data record with search key value } k \rangle$
  - (3) Unclustered Index: data entry separated from data record:  $\langle k, \text{list of rids of data records with search key } k \rangle$ , useful when search key is not unique (not a candidate key).
- What is the performance (cost of retrieving records) difference between clustered and un-clustered index?

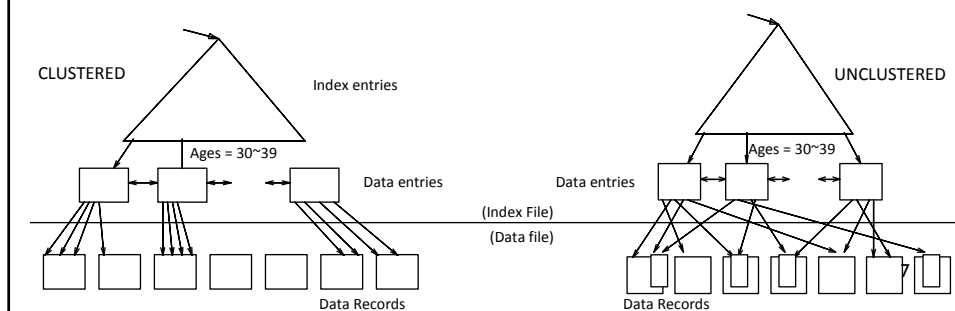
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## Review: Clustered vs. Unclustered Index

- Examples: retrieve all the employees of ages 30~39.
  - What is the worst-case cost (# disk page I/Os) of clustered index?
  - What is the worst-case cost of unclustered index?

*Cost = number of pages retrieved*

*mr = # matched records; mp = # pages containing matched records*

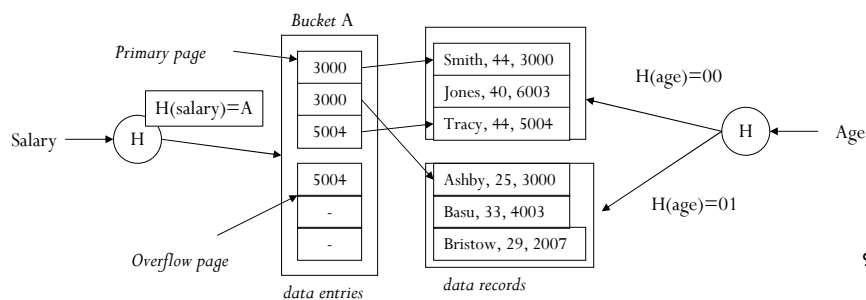


## Review: Two General indexing techniques

- Hash-structured indexing or tree-structured indexing
- Briefly describe them and ask you to compare them on cost of
  - Equality search: find all employees of age 30.
  - Range search: find all the employees of ages 30~39.

## Hash-Based Indexes

- Data entries (key, rid) are grouped into buckets.
- Bucket = *primary* page plus zero or more *overflow* pages.
- *Hashing function h*:  $h(r)$  = bucket in which record  $r$  belongs.  $h$  looks at the *search key* fields of  $r$ .
- If Alternative (1) is used, the buckets contain the data records.



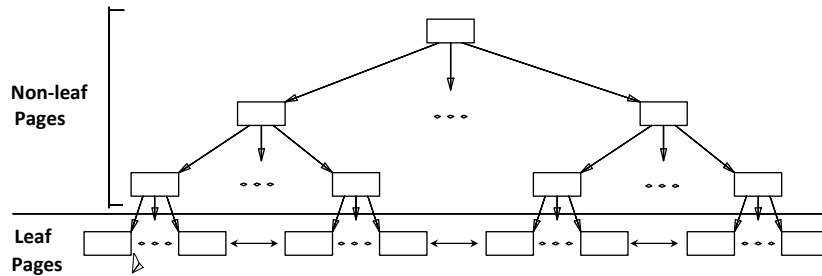
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## Hash-based Indexes (Cont)

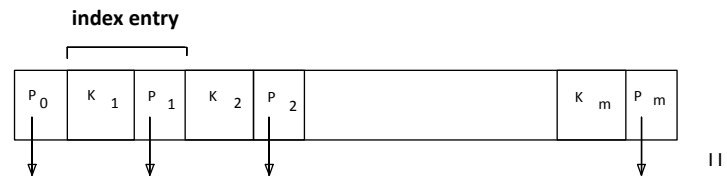
- Search on key value:
  - Apply key value to the hash function  $\rightarrow$  bucket number
  - Retrieve the primary page of the bucket. Search records in the primary page. If not found, search the overflow pages.
  - Cost of locating rids: # pages in bucket (small)
- Insert a record:
  - Apply key value to the hash function  $\rightarrow$  bucket number
  - If all (primary & overflow) pages in that bucket are full, allocate a new overflow page.
  - Cost: similar to search.
- Delete a record
  - Cost: similar to search.

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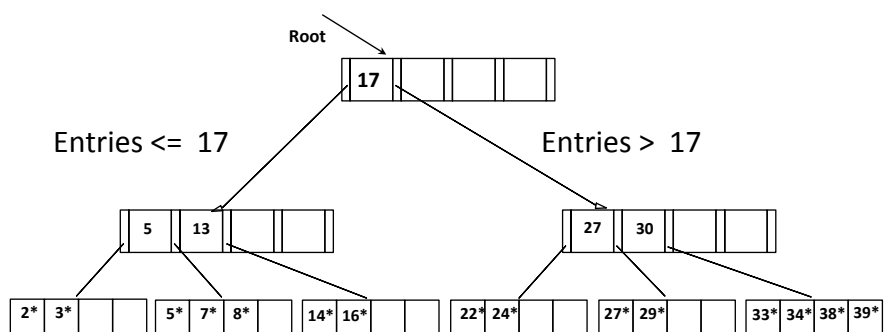
## B+ Tree Indexes



Leaf pages contain data entries, and are chained (prev & next)  
 Non-leaf pages contain index entries and direct searches:



## Example B+ Tree



- Find 7\*, 29\*? 15\* < age < 30\*
- Insert/delete: Find data entry in leaf, then change it. Need to adjust parent sometimes.
  - And change sometimes bubbles up the tree (keep the tree balance)
- More details about tree-based index in Chapter 10.

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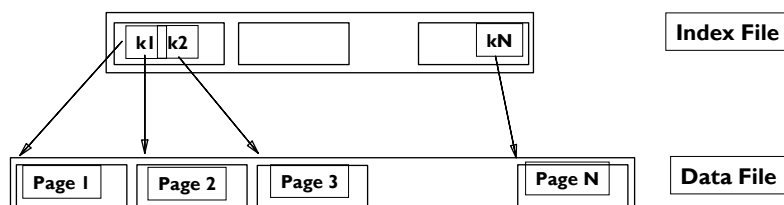
## Tree vs. Hash-Structured Indexing

- Tree index supports both *range searches* and *equality searches* efficiently.
  - Why efficient range searches?
    - Data entries (on the leaf nodes of the tree) are sorted.
    - Perform equality search on the first qualifying data entry + scan to find the rests.
    - Data records also need to be sorted by search key in case that the range searches access record fields other than the search key.
- Hash index supports equality search efficiently, but not range search.
  - Why inefficient range searches?
    - Data entries are hashed (using a hash function), not sorted.

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## The Origin of [Tree] index

- Range search: *Find all students with gpa > 3.0*
  - Sorted data file: binary search to find first such student, then scan to find others.
  - Cost?
- Simple solution: create a smaller index file.
  - Cost of binary search over index file is reduced.



\* Can do binary search on (smaller) index file!

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## Why tree index?

- But, the index file can still be large.
  - The cost of binary search over the index file can still be large.
  - Can we further reduce search cost?
- Apply the simple solution again: create multiple levels of indexes.
  - Each index level is much smaller than the lower index level. This index structure is a tree.
- Say if a tree node is an index page holding, e.g., 100 indexes.
  - A tree with a depth of 4 (from the root index page to the leaf index page) can hold over  records.
  - The cost of search is  page access.

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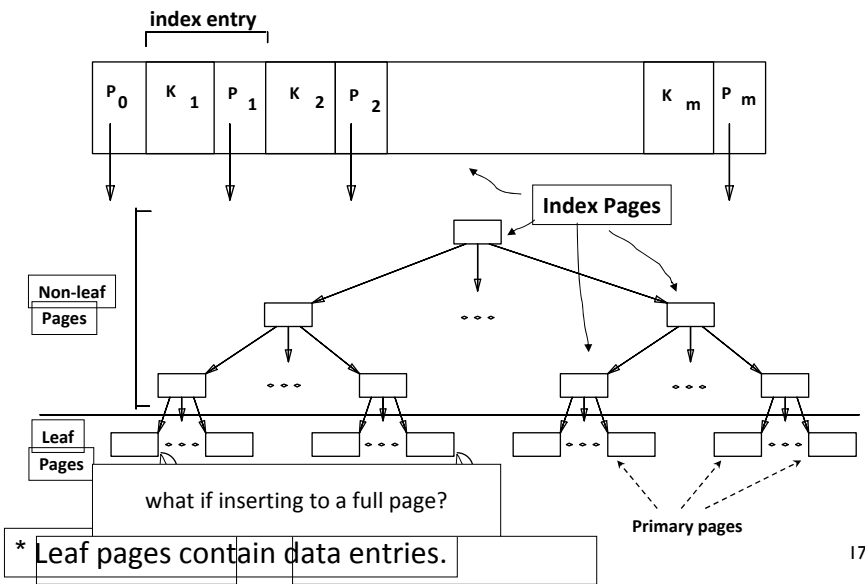
## ISAM and B+ Tree

- Two tree-structured indexings:
  - ISAM (Indexed Sequential Access Method): static structure.
    - Assuming that the file does not grow or shrink too much.
  - B+ tree: dynamic structure
    - Tree structure adjusts gracefully under inserts and deletes.
- Analyze cost of the following operations:
  - Search
  - Insertion of data entries
  - Deletion of data entries
  - Concurrent access.

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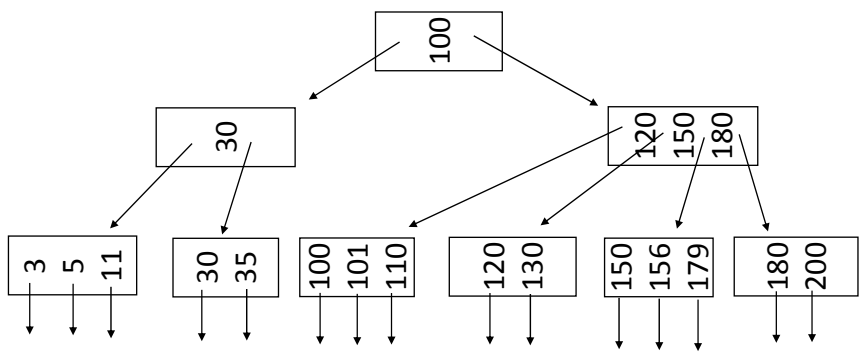


# ISAM



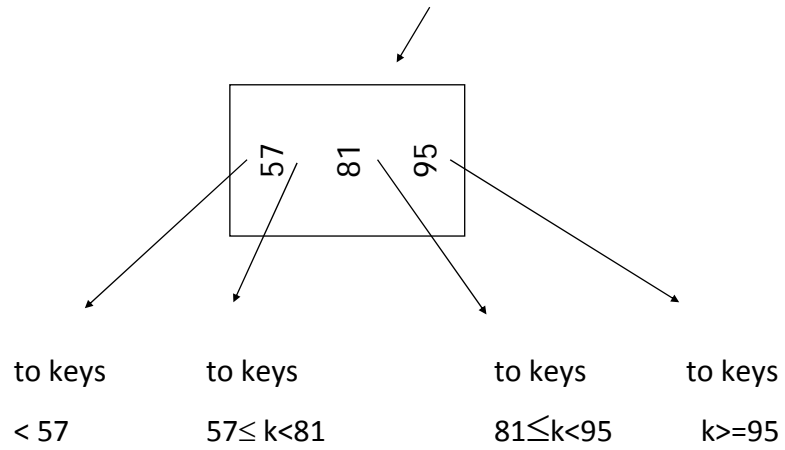
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# Example



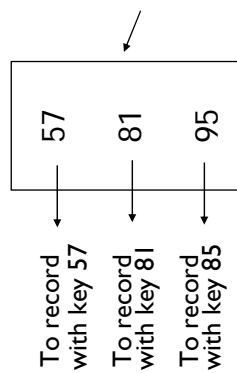
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## Non-leaf node



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## Leaf node



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## Comments on ISAM

- File creation:
  - Assume that data records are present and will not change much in the future.
  - Sort data records. Allocate data pages for the sorted data records.
  - Sort data entries based on the search keys. Allocate leaf index pages for sorted data entries sequentially.

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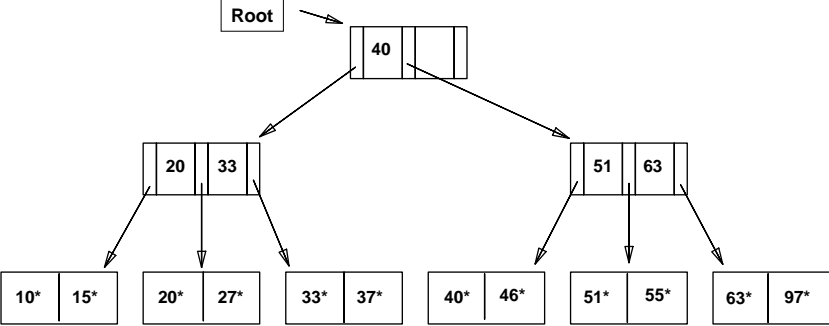
## ISAM Operations

- Search: Start at root; use key comparisons to go to leaf.
  - Cost =  $\log_F N$ , where  $F$  = # entries/index page,  $N$  = # leaf pages
- Insert: Find the leaf page and put it there. If the leaf page is full, put it in the overflow page.
  - Cost = search cost + constant (assuming little or no overflow pages)
- Delete: Find and remove from the leaf page; if empty overflow page, de-allocate.
  - Cost = search cost + constant (assuming little or no overflow pages)

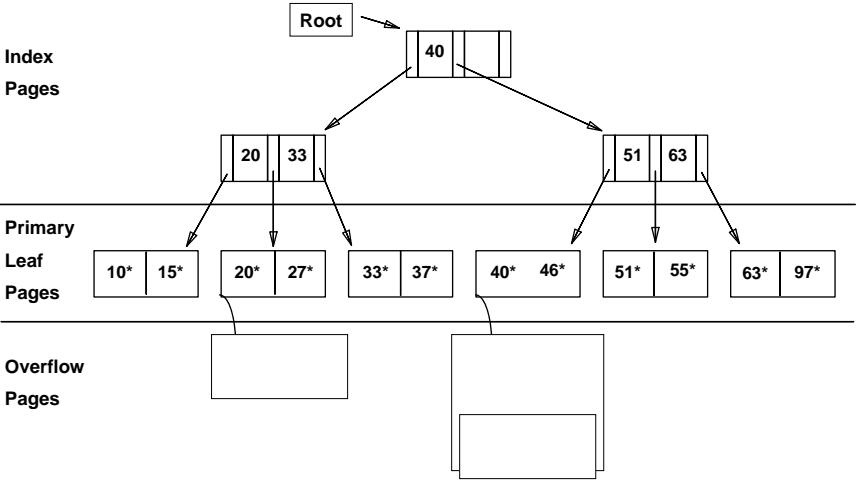
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# Example ISAM Tree

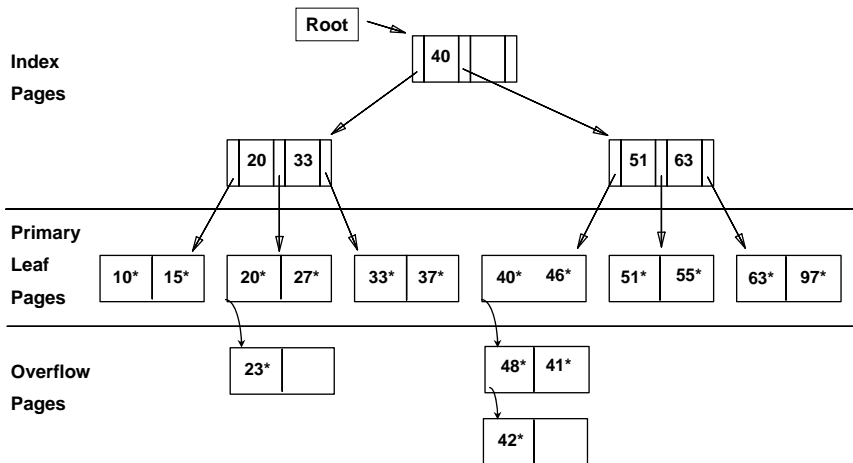
- Each node can hold 2 entries; no need for 'next-leaf-page' pointers in primary pages. Why not?
  - Primary pages are allocated sequentially at file creation time.



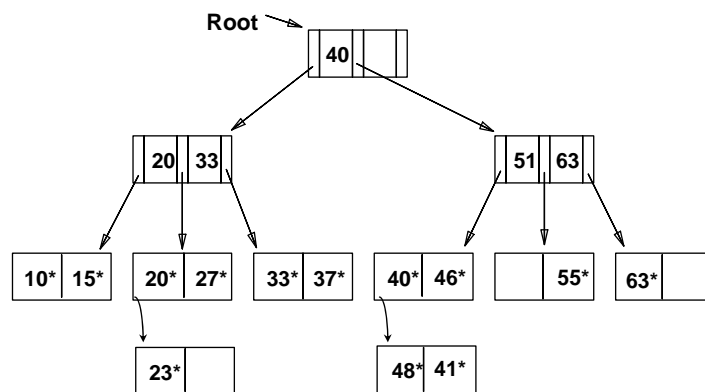
# After Inserting 23\*, 48\*, 41\*, 42\* ...



## ... Now Deleting 42\*, 51\*, 97\*



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\* Note that 51\* appears in index levels, but not in leaf!

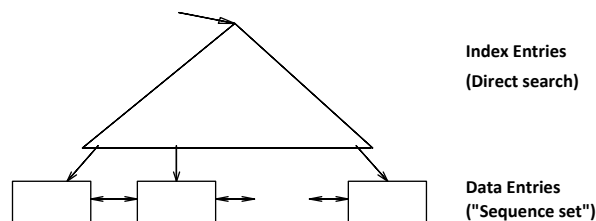
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## Properties of ISAM Tree

- Insertions and deletions affect only the leaf pages, not the non-leaf pages
  - index in the tree is static.
- Static index tree has both advantages & disadvantages.
  - Advantage:  access.
  - Disadvantage:  leading to poor
- ISAM tree is good when data does not change much.
  - To accommodate some insertions, can leave the primary pages 20% empty.
- How to solve the disadvantage in ISAM tree?
  - B+ tree can support file growth & shrink efficiently, but at the cost of <sub>27</sub> locking overhead.

## B+ Tree

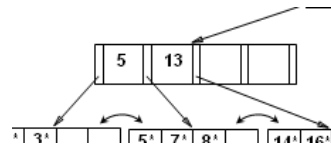
- It is similar to ISAM tree-structure, except:
  - It has no overflow chains (this is the cause of poor performance in ISAM).
    - When an insertion goes to a leaf page becomes full, a new leaf page is created.
  - Leaf pages are not allocated sequentially. Leaf pages are sorted and organized into doubly-linked list.
  - Index pages can grow and shrink with size of data file.



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## Properties of B+ Tree

- Keep tree height-balanced.
  - Balance means that distance from root to all leaf nodes are the same .
- Minimum 50% occupancy (except for root)
  - Each index page node must contain  $d \leq m \leq 2d$  entries.
  - The parameter  $m$  is the number of occupied entries.
  - The parameter  $d$  is called the order of the tree (or  $\frac{1}{2}$  node capacity)



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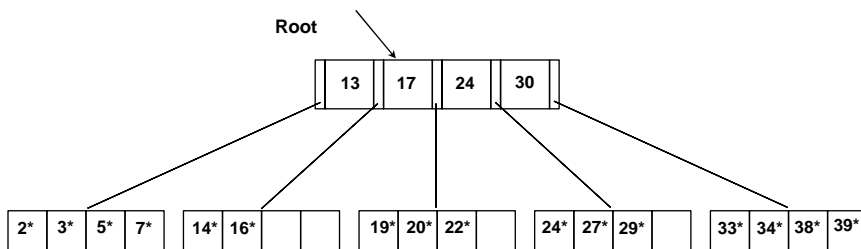
## More Properties of B+ Tree

- Cost of search, insert, and delete (disk page I/Os):
  - $\Theta(\text{height of the tree}) = \Theta(\log_{m+1} N)$ , where  $N = \#$  leaf pages
- Supports equality and range-searches efficiently.
- B+ tree is the most widely used index.

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## Example B+ Tree

- Search begins at root, and key comparisons direct it to a leaf (same as in ISAM).
- Search for 5\*, 15\*, all data entries  $\geq 24^*$  ...



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## B+ Trees in Practice

- Typical order: 100. Typical fill-factor: 66%.
  - average fanout = 133
- Typical capacities:
  - Height 4:  $133^4 = 312,900,700$  records
  - Height 3:  $133^3 = 2,352,637$  records
- Can often hold top levels in buffer pool:
  - Level 1 = 1 page = 8 Kbytes
  - Level 2 = 133 pages = 1 Mbyte
  - Level 3 = 17,689 pages = 133 Mbytes

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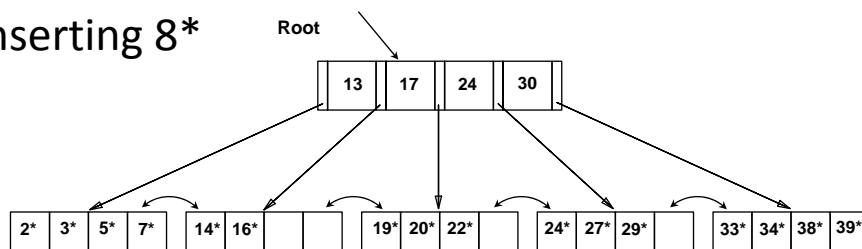


# Inserting a Data Entry into a B+ Tree

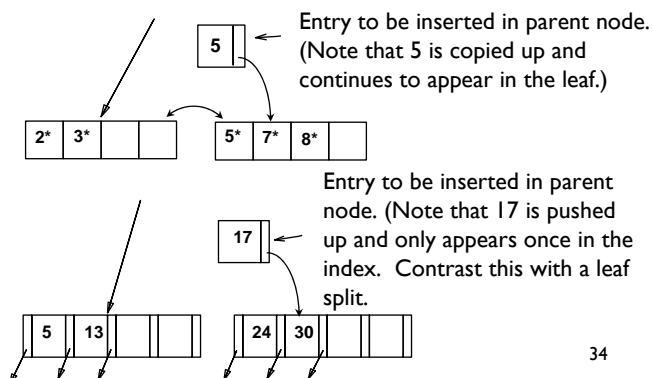
- Find correct leaf  $L$ .
- Put data entry onto  $L$ .
  - If  $L$  has enough space, *done!*
  - Else, must *split*  $L$  (into  $L$  and a new node  $L2$ )
    - Redistribute entries evenly, **copy up** middle key.
    - Insert index entry pointing to  $L2$  into parent of  $L$ .
- This can happen recursively
  - To split index node, redistribute entries evenly, but **push up** middle key. (Contrast with leaf splits.)
- Splits “grow” tree; root split increases height.
  - Tree growth: gets *wider* or *one level taller at top*.

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## Inserting 8\*

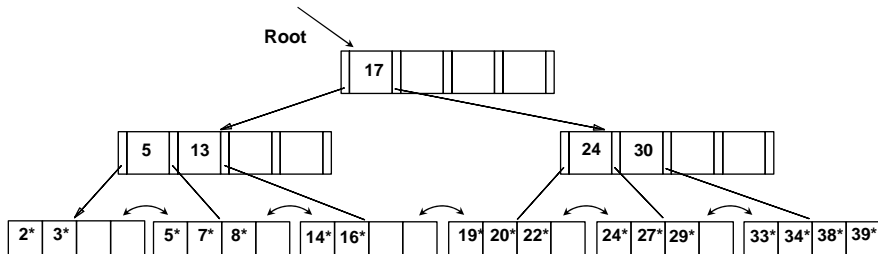


- Why is minimum occupancy always guaranteed in both leaf and index pg splits?
- What is the difference between *copy-up* and *push-up*?
- How to avoid splitting?



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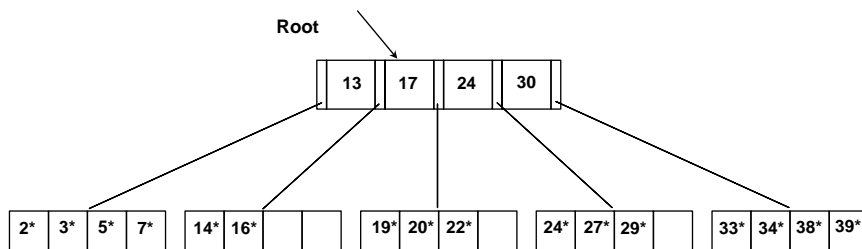
## Example B+ Tree After Inserting 8\*



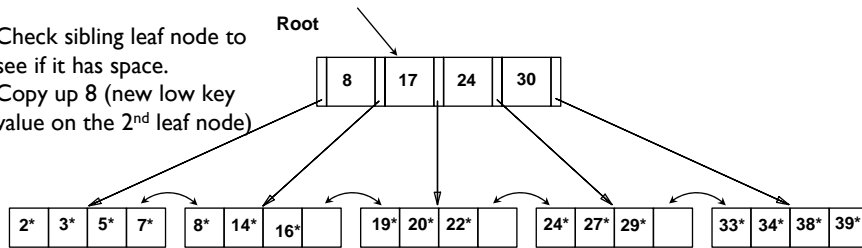
Root was split, leading to increase in height.  
Avoid split by re-distributing entries.

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## Redistribution after Inserting 8\*



Check sibling leaf node to see if it has space.  
Copy up 8 (new low key value on the 2<sup>nd</sup> leaf node)



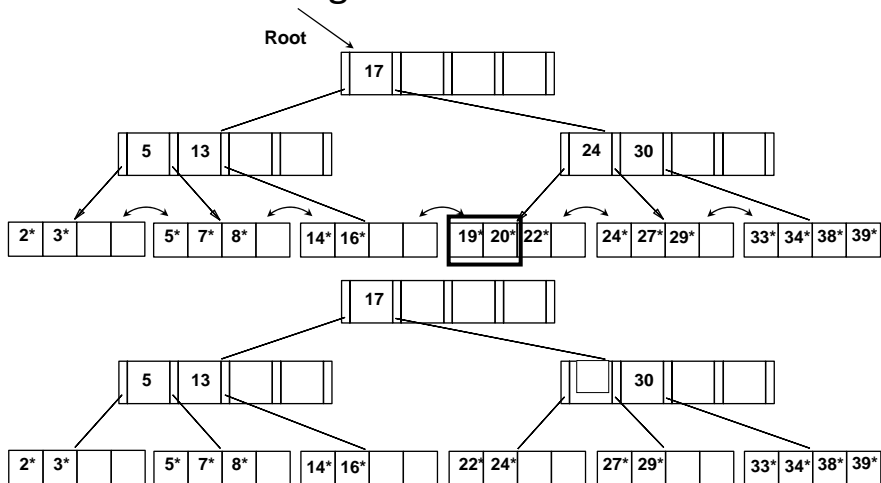
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## Deleting a Data Entry from a B+ Tree

- Start at root, find leaf  $L$  where entry belongs.
- Remove the entry.
  - If  $L$  is at least half-full, *done!*
  - What if  $L$  is less than half-full?
    - Try to re-distribute, borrowing from *sibling* (adjacent node with same parent as  $L$ ).
    - What if re-distribution fails?
      - merge  $L$  and sibling.
- If merge occurred, must delete index entry (pointing to  $L$  or sibling) from parent of  $L$ .
- Merge could propagate to root, decreasing height.

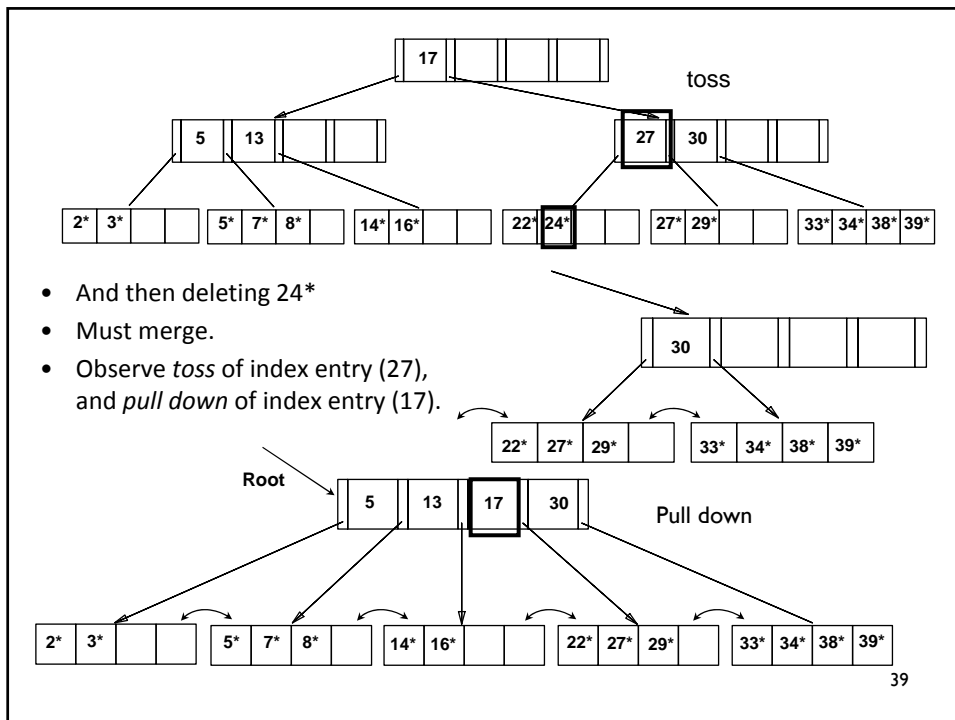
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### Tree After Deleting 19\* and 20\* ...



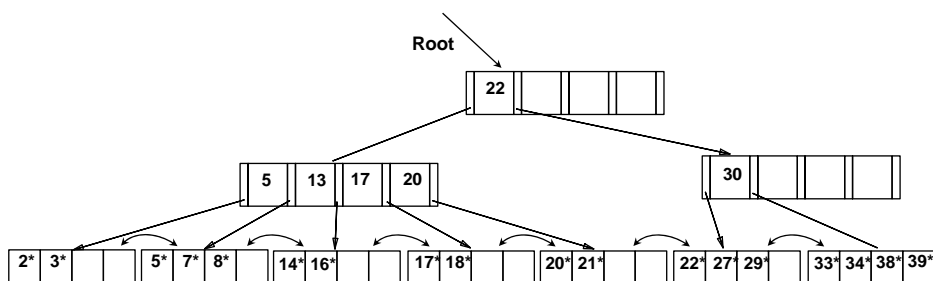
- Deleting 19\* is easy.
- Deleting 20\* is done with re-distribution. Notice how middle key is *copied up*.

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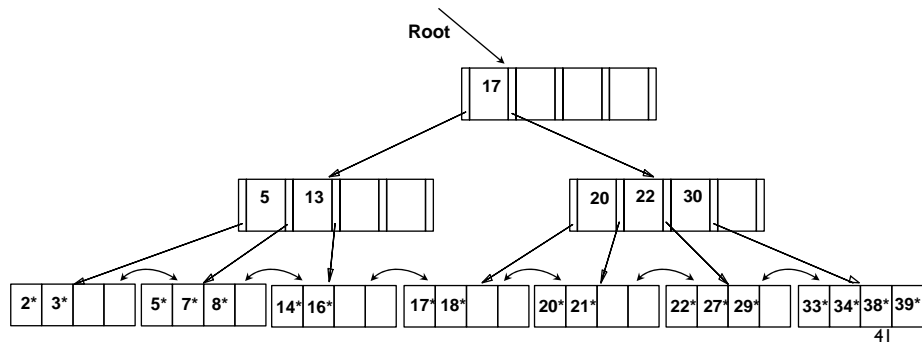
## Example of Non-leaf Re-distribution

- Tree is shown below *during deletion* of 24\*. (What could be a possible initial tree?)
- May re-distribute entry from left child of root to right child.



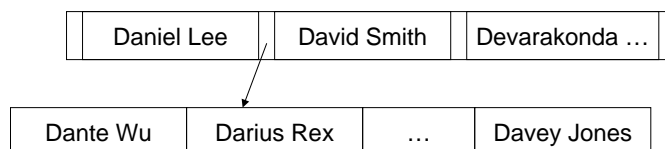
## After Re-distribution

- Intuitively, entries are re-distributed by *pushing through* the splitting entry in the parent node.
- It suffices to re-distribute index entry with key 20; we've re-distributed 17 as well for illustration.



## Prefix Key Compression

- Important to increase fan-out. (Why?)
- Key values in index entries only 'direct traffic'; can often compress them.
  - Compress "David Smith" to "Dav"? How about "Davi"?
  - In general, while compressing, must leave each index entry greater than every key value (in any subtree) to its left.



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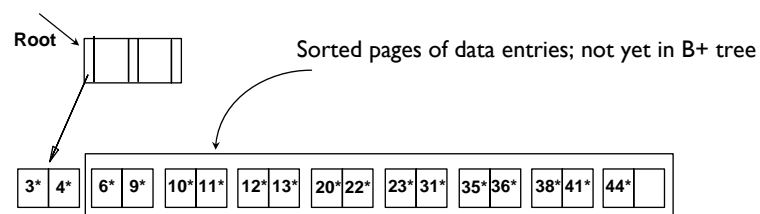
## Bulk Loading of a B+ Tree

- Given a large collection of records
- We want to create a B+ tree on some field
- How to do it slowly?
  - Insert each record repeatedly. What is the cost of building index?
    - # entries \*  $\log_F(N)$ , where F = fan-out, N = # index pages
- How to do it quickly?
  - Insert at the unit of a page.

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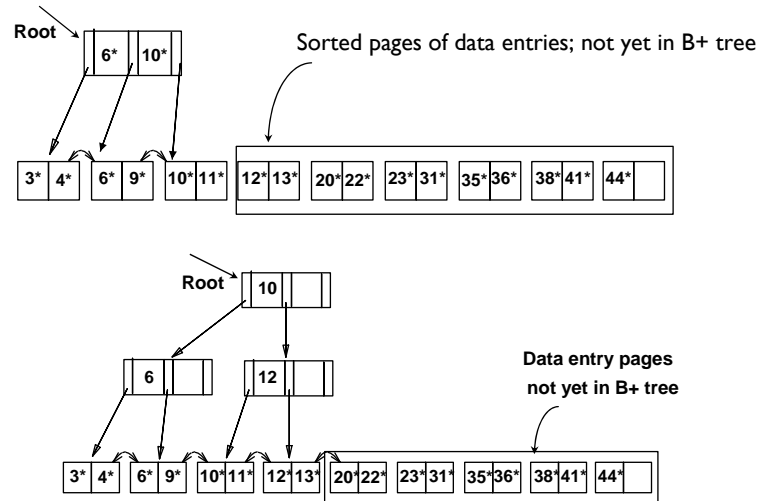
## Bulk Loading of a B+ Tree

- Bulk Loading can be done much more efficiently.
  - Step 1: Sort data entries. Insert pointer to first (leaf) page in a new (root) page.



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## Bulk Loading(Conti)

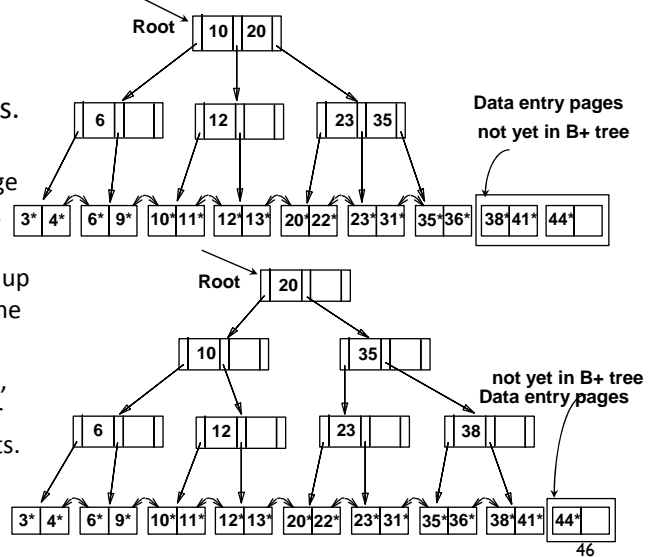


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## Bulk Loading (Contd.)

- Step 2: Build Index entries for leaf pages.

- Always entered into right-most index page just above leaf level. When this fills up, it splits. (Split may go up right-most path to the root.)
- Cost = # index pages, which is much faster than repeated inserts.



## Summary of Bulk Loading

- Option 1: multiple inserts.
  - More I/Os during build.
  - Does not give sequential storage of leaves.
- Option 2: Bulk Loading
  - Fewer I/Os during build.
  - Leaves will be stored sequentially (and linked, of course).
  - Can control “fill factor” on pages.

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## A Note on ‘Order’

- *Order* (the parameter **d**) concept denote minimum occupancy on the number of entries per index page.
  - But it is not practical in real implementation. Why?
    - Index pages can typically hold many more entries than leaf pages.
    - Variable sized records and search keys mean different nodes will contain different numbers of entries.
- *Order* is replaced by physical space criterion (*‘at least half-full’*).

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